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Reconstruction of thermal defects from photothermal images

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Abstract

The paper reports on 2 methods to get depth dependend information about thermal properties from photothermal measurements. First, an inversion technique is suggested to calculate the depth profile of either k or co. Second, a deconvolution technique making use of the photothermal point spread function is presented to estimate depth, size and strength of buried localized thermal defects.

Nomenclature

Subscripts

b

calc

ref

0

bulk

calculated

i.m.n. running indexes

measured

reference

homogeneous

Greek symbols

density

thermal wave number

ø

σ

- A signal amplitude
- A' amplitude ratio
- c specific heat
- D thermal defect distribution meas
- f frequency
- F imaginary content of D
- G photothermal point spread
- function (PSF)
- H absorbed heat density
- k thermal conductivity
- K photothermal contrast
- N number of measurements
- P' phase difference
- P signal phase
- S complex photothermal signal
- W window function
- x,y lateral coordinates
- z depth coordinate

1. Introduction

Time resolved thermography enables us to see behind the surface of optically opaque samples. Thermal waves generated by periodical sample heating provide information about hidden defects and inhomogeneities. Because of their dispersive propagation velocity $v(f) = 2 (\pi k f/\varrho c)^{1/2}$ they show a characteristic phase lag to excitation depending both on the distance between irregularity and surface and on modulation frequency.

The advantage of surface detected thermal waves was exploited by us

- to reconstruct the depth profile of thermal properties (as it is of interest in case of dopant profiles, hardening layers,..)

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- to reconstruct depth, shape and strength of localized perturbations of thermal properties within an otherwise homogeneous material.

2. Reconstruction of thermal conductivity depth profile

2.1 Mathematical approach of inversion

The inhomogeneous heat diffusion equation can be solved analytically in the case of linearly inhomogeneous k or ϱc [1]. So, for example, it is possible to calculate analytically the surface temperature of a surface absorbing sample with a k-profile shaped like a polygonal curve.

Knowing this result it is possible to invert the measured surface temperature by an inversion procedure and to obtain the polygonal k-profile. The approach is the following:

The surface temperature depending on modulation frequency is measured by an appropriate photothermal technique (eg. radiometrically), yielding the complex photothermal signal

$$S(0 t) = \Delta(f) e^{iP(f) + i2\pi f t}$$

It is assumed that i) the property gc is constant inside the whole sample and ii) the bulk thermal conductivity is known.

For further considerations we have to take into account the measured curves of the amplitude ratio $A' = A/A_b$ and the phase difference $P' = P - P_b$. The subscript b denotes the pure bulk material used as a reference. To reconstruct approximately the k-profil of the sample under test by a polygonal curve we suppose the subsurface region being subdivided into sublayers of equal thickness Δz . z_i are the interface depths.

Approximately we obtain the surface value $k_0 = k(z_0)$ by the relation

$$k_0 = k_b/(A'(f_0))^2$$

where the measured amplitude ratio is taken at the maximum adjustable frequency f_0 .

Starting from k_0 we approximate k at each sublayer interface z_m . Within each sublayer k varies linearly. If we know all the k values from z_0 to z_m , how can we get $k(z_{m+1}) = k(z_m + \Delta z) = k_{m+1}$?

Decreasing the modulation frequency from f_m to a lower value f_{m+1} the thermal waves provide additional information about the sublayer between z_m and z_{m+1} . f_{m+1} is obtained from the relation

$$z_{m+1} - z_m = dz = [(k_h - k_m)/2\pi gc]^{1/2} [(1/f_m)^{1/2} - (1/f_{m+1})^{1/2}]$$
(3)

The next value k_{m+1} can be obtained by a least square fit comparing either the measured amplitude ratios or phase differences with the corresponding calculated ones

$$(\sum_{i} [A'_{meas}(f_i) - A'_{calc}(f_i)]^2 / [N(f_{m+1}) - 1])^{1/2} = Min^{1/2}$$
(4)

 $N(f_{m+1})$ is the number of all the measurement frequencies f_i in the range from f_o to f_{m+1} . Equ.(4) has to be minimized only with respect to K_{m+1} . By this approach we "build-up" the kprofile from the surface to the depth using the data from very high modulation frequencies to lower ones. The applicated least square technique allows for a good reconstruction also in the case of unproperly chosen surface conductivity.

A similar inversion procedure can be carried out in the case of a sample with gradually linearly inhomogeneous ec but constant k.

2.2 Numerical inversion results from synthesized k-profiles

(2)

(1)

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We tested the ability of the inversion technique by presuming a polygonal k-profile. The photothermal signal which is proportional to the surface temperature was calculated using the analytical solution of the 1-dimensional heat diffusion equation. Then the frequency dependent A' and P'curves were estimated.

Summarizing all of our numerical inversion results we may conclude that inverting the phase data gives a better k-profile reconstruction than inverting the amplitude data. This corresponds to the well known behavior of the 1-dimensional thermal waves to produce higher contrast in phase than in amplitude from deeply buried interfaces.

The performance of the proposed inversion technique is demonstrated in Fig.1. Here a nonmonotonic k-profil has to be reconstructed from noisy phase measurements. The random phase error was assumed to be 0.2°. Subdividing the subsurface region into 25 sublayers gives a good approximation of the actual profile. The approximation can be improved by increasing the number of sublayers, decreasing their thicknesses and higher grading the slope steps in k.

Moreover, the proposed technique is rather insensitive to noise of the measurement, as it is shown in the next figure. In this example the phase noise was assumed to be 1° , a rather high but realistic value (amplitude noise needed for the estimation of k_o was 10% in this case). Nevertheless, the k-profile could be reconstructed succesfully from noisy data. In Fig.2 several reconstructed profiles are shown corresponding to different "experimental" realizations of the same synthesized profile. The individual reconstructions are close together demonstrating the good convergence of the method.

3. Reconstruction of localized thermal defects

3.1 Deconvolution using the photothermal point spread function

Due to the diffusive nature of thermal waves and their mutual interference the images of buried objects are blurred. Resemblance between image and object fades out with increasing depth of the object.

At photothermal imaging there arises the necessity to reconstruct buried defects from photothermal images. We present a first attempt to make use of the photothermal point spread function (as defined in [2]) for object reconstruction. The method is based on the property of the photothermal contrast image which can be expressed mathematically as a convolution integral of the point spread function G and a distribution function D of thermal inhomogeneities. The measurable photothermal contrast as defined in [3] can be written as

$$K(x,y) = \Delta z \int \int G(x-x',y-y',z_0) D(x',y',z_0) dx' dy'$$

assuming a defect of small thickness Δz , buried at depth z_0 . D(x,y,z) describes the distribution of the normalized parameter deviations

$$D_{k} = (k(x,y,z) - k_{0}) / k_{0}, \quad D_{ec} = (\varrho c(x,y,z) - \varrho c_{0}) / \varrho c_{0}$$
(6)

We have to keep in mind that G depends on both the defect depth and the type of thermal inhomogeneity (thermal conductivity and/or thermal density).

From the measured complex valued contrast $K = K_A + iK_P$ we can obtain the defect distribution by appropriate deconvolution. By Fourier transforming all mathematical expressions FT{D} can be obtained as ratio FT{K}/FT{G}. But, in the experiments, there are at least 2 problems:

1) K results from noisy measurements.

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2) Both the defect depth z_0 and defect type usually are unknown and have to be estimated by the reconstruction procedure.

To overcome the noise difficulties we have to multiply $FT\{K\}$ by an appropriately chosen window spektrum $FT\{W\}$

$$D = 1/az \ FT^{1} \{ FT\{K\} FT\{W\} / FT\{G\} \}$$
(7)

Obviously, we only obtain the true defect distribution $D(x,y,z_0)$ as the inverse Fourier transform if we deconvolute it with the correct PSF (taken at the correct depth $z = z_0$ and knowing the thermal type of defect). Of course, these values are unknown, and we have to determine the correct PSF G from an independent criterion. For simplicity, we restrict our efforts to the search of the unknown defect depth z_0 and deconvolute the "measured" contrast K(x,y,) with a number of PSF's taken at guessed depths z. Complex valued defect distributions are obtained whose imaginary content F is quantified by

$$F = [\sum Im {D(x,y,z)}^2]^{1/2}$$

(8)

Because $D(x,y,z_0)$ has to be a real valued function we will find the correct depth $z = z_0$ if F = 0 or, in the presence of noise, if F has a minimum among the various depths investigated. Numerically, this means to find the global minimum of the function F = F(z). Fig.3 shows the typical behavior of F(z) in the surrounding of z_0 with its global minimum.

3.3 Reconstruction of a buried strip defect

We designed a sample which matches as much as possible the assumptions made by the inversion model:

- small thermal difference between defect and surrounding medium,
- sample is a surface absorber (metal)
- the defect thickness is small compared to both the defect width and the thermal diffusion length.

Also, the assumption of signal being proportional to the averaged surface temperature was satisfied by wide aperture radiometric detection (active area of the detector: 1 mm²). Due to experimental conditions, the assumption of pointlike excitation was not fulfilled. This could result in a further blurring of the image.

The sample was made out of a soldering tin-alloy (96%Sn, 4%Ag). The defect strip was embedded 200 μ m below the surface, 5 mm from each side of the sample to avoid reflection of the thermal waves even at low frequencies. The strip consists of stainless steel, it is 50 μ m thick and 500 μ m wide. The raw data were recorded within the frequency range from 15 to 1400 Hz, selected scans are given in Fig.4. From these data amplitude and phase contrast have been calculated followed by smoothing with window functions adapted for the problem.

After calculating Equs.(7) and (8) we found the defect being situated at depth $z_0 = 270\mu m$ (actual: 225 μ m) and having the "contour" as shown in Fig.5. A strip-like shape of width about 700 μ m (actual: 500 μ m) has been found. This broadening is caused, among other reasons, by the finite width of the heating laser beam. From the magnitude of the center contrast, especially from its frequency dependence, we could estimate the magnitude of the deviations in k and ϱc to be $\Delta k/k_0 = 0.7$ (actual: 0.7) and $\Delta \varrho c/\varrho c_0 = -1.25$ (actual: -0.4). The good correspondence between actual and calculated k-distortion has to be pointed out. The larger difference of the ϱc -distortion may be due to its generally smaller contribution to the photothermal signal.

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Fig.3: Dependence of the imaginary contrast of D on guessed defect depths z (true depth z_o)



Fig.4: Radiometric scans across the buried strip at different frequencies



